

Approaching NSP-EMD with B-Splines

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Mathematisches Institut
Universität zu Köln

hosted by

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introduction

intrinsic mode function (IMF) (1/2)

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- ▶ Physical reasonability.

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- ▶ Physical reasonability.
- ▶ Slowly varying amplitude.

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- ▶ Physical reasonability.
- ▶ Slowly varying amplitude.
- ▶ Slowly varying frequency.

introduction

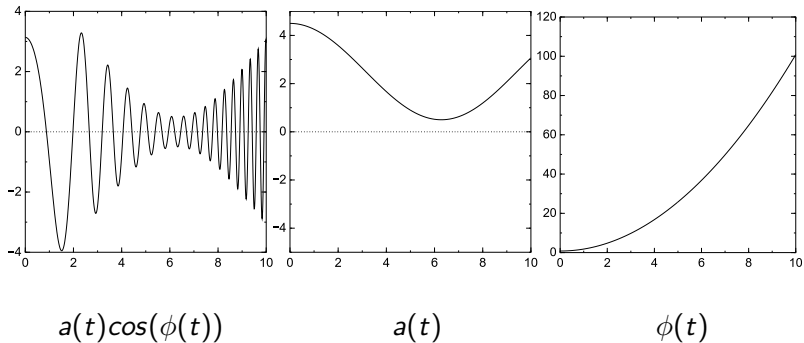
intrinsic mode function (IMF) (2/2)

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empirical mode decomposition (EMD) (N.E. Huang et al., 1998)

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$$s(t) = \sum_{k=0}^w s_k(t) + r_{w+1}(t), \quad s_k \in \mathcal{I}$$

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$$\begin{aligned} r_0(t) &= s(t) \\ r_{k+1}(t) &= r_k(t) - s_k(t) \end{aligned}$$

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$$r_0(t) = s(t)$$
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goal

Find a_k and ϕ_k .

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operator-based signal separation (OSS) (S. Peng et al., 2008) (1/2)

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Find differential operator $\mathcal{D}_{P_k, Q_k, R_k}$ analytically such that

$$\mathcal{D}_{P_k, Q_k, R_k} s_k = 0.$$

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Let $P_k = P_k(a_k, \phi_k)$, $Q_k = Q_k(a_k, \phi_k)$, $R_k = R_k(a_k, \phi_k)$.
Find differential operator $\mathcal{D}_{P_k, Q_k, R_k}$ analytically such that

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Solve

$$\begin{aligned} (P_k, Q_k, R_k) &= \arg \min_{(\tilde{P}, \tilde{Q}, \tilde{R})} \|Q_1(r_k - \tilde{s})\| \\ &\text{s.t. } \mathcal{D}_{\tilde{P}, \tilde{Q}, \tilde{R}} \tilde{s} = 0 \\ &\|Q_2 \tilde{P}\| \leq \tau \\ &\|Q_3 \tilde{Q}\| \leq \tau \\ &\|Q_4 \tilde{R}\| \leq \tau \end{aligned}$$

with $\tau > 0$, $Q_1, Q_2, Q_3, Q_4 \in \{D^0, D^1, \dots\}$ regularization operators, $\tilde{P} := P_k(\tilde{a}, \tilde{\phi})$, $\tilde{Q} := Q_k(\tilde{a}, \tilde{\phi})$, $\tilde{R} := R_k(\tilde{a}, \tilde{\phi})$ and $\tilde{s} := \tilde{a}(t)\cos(\tilde{\phi}(t))$.

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operator-based signal separation (OSS) (S. Peng et al., 2008) (2/2)

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unconstrained formulation

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$$(P_k, Q_k, R_k) = \arg \min_{(\tilde{P}, \tilde{Q}, \tilde{R})} \|\mathcal{D}_{\tilde{P}, \tilde{Q}, \tilde{R}} \tilde{s}\| + \lambda \|Q_1(r_k - \tilde{s})\| + \mu (\|Q_2 \tilde{P}\| + \|Q_3 \tilde{Q}\| + \|Q_4 \tilde{R}\|)$$

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Want to control \tilde{s} , and thus s_k , in some way.

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null space pursuit (NSP) (S. Peng, W.-L. Hwang et al., 2010)

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Introduce leakage factor γ .

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Controls retainment of information in residual signal.

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Does it really help understanding EMD?

vanishing operators

example (X. Hu, S. Peng, W.-L. Hwang, 2012)

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$$P_k(a_k, \phi_k) = -2 \frac{a'_k}{a_k},$$

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$$R_k(a_k, \phi_k) = 0,$$

$$\mathcal{D}_{P_k, Q_k, R_k} = \frac{d^2}{dt^2} + P_k(t) \frac{d}{dt} + Q_k(t).$$

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Let $a''_k(t) \neq 0$.

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Let $a''_k(t) \neq 0$. It holds

$$\mathcal{D}_{P_k, Q_k, R_k} s_k(t) = \frac{a''_k(t)}{a_k(t)} \neq 0.$$

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$$\text{Let } A_k(a_k) := \frac{a'_k}{a_k}, \Omega_k(\phi_k) := \frac{1}{(\phi'_k)^2}.$$

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Can we find a simple general form?

B-Splines

approach

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approach

- ▶ Express functions, e.g. the signal, as B-splines of order $k \geq 1$:

$$s(t) = \sum_{i=0}^{n-1} s_i B_{i,k}(t) \in \mathcal{C}^{k-2}.$$

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- ▶ Least-Squares-Fit of time series data.

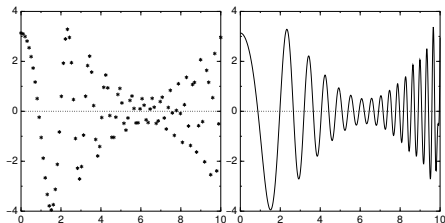
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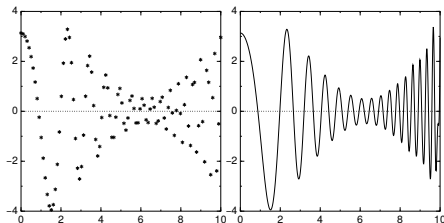
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- ▶ Generate extended grid with $q \geq 0$ intermediate points between spline knots.

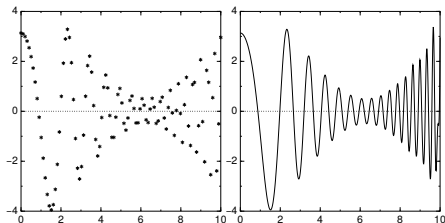
B-Splines

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- ▶ Express functions, e.g. the signal, as B-splines of order $k \geq 1$:

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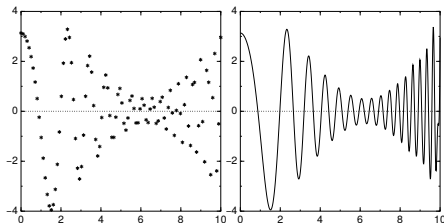
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- ▶ Directly optimize over (a_k, ϕ_k) .

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- ▶ Constant time evaluation of $s_k^{(m)}$ only with a_k and ϕ_k using LEIBNIZ' rule and FAÀ DI BRUNO's formula after preprocessing multinomials and partitions.

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We can do better than that.

proposed optimization problem

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We can e.g. set $c(\tilde{a}, \tilde{\phi}) = \|Q(r_k - \tilde{s})\|$ with $Q \in \{D^0, \dots, D^{k-2}\}$.

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- ▶ Compare with other approaches.